# Proximal Oracles for Optimization and Sampling

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## Algorithm design for optimization and sampling using proximal oracles.



(a) Optimization,  $\min f(x)$ 



(b) Sampling, samp  $\exp(-f(x))$ 

## Gradient descent

$$x_{k+1} = x_k - \eta \nabla f(x_k)$$

 $\bullet$  Unadjusted Langevin algorithm (ULA),  $\nu(x) \propto \exp(-f(x))$ 

$$x_{k+1} = x_k - \eta \nabla f(x_k) + \sqrt{2\eta}z, \quad z \sim \mathcal{N}(0, I)$$

equivalent to sampling  $x_{k+1} \sim p(y|x_k)$  where

$$p(y|x_k) \propto \exp\left(-\frac{1}{2\eta}\|x - (x_k - \eta \nabla f(x_k))\|^2\right)$$

<ロト < 部ト < 言ト < 言ト 言 のへで 3/28 Langevin dynamics

$$\mathrm{d}X_t = -\nabla f(X_t)\mathrm{d}t + \sqrt{2}\mathrm{d}B_t$$

Fokker-Planck equation (continuity equation)

$$\frac{\partial \rho_t}{\partial t} = \nabla \cdot \left( \rho_t \nabla \log \frac{\rho_t}{\nu} \right) = -\mathsf{grad}_{\rho_t} H_{\nu}(\rho_t)$$

Jordan, Kinderlehrer, and Otto 1998: Langevin dynamics in space corresponds to the gradient flow of the relative entropy in the space of measures with the Wasserstein metric

$$\min_{\rho \in \mathcal{P}_2(\mathbb{R}^d)} \left\{ H_{\nu}(\rho) = \int \rho \log \frac{\rho}{\nu} \right\}$$

ULA is biased:  $\rho_k \to \bar{\rho}$  as  $k \to \infty$ , but  $H_{\nu}(\rho_{\infty}) > 0$ .

Metropolis-adjusted Langevin algorithm: take ULA as a proposal density  $p(\cdot|x_k)$ , draw  $y_k \sim p(y_k|x_k)$ , and accept  $y_k$  with probability

$$\min\left\{1, \frac{\nu(y_k)p(x_k|y_k)}{\nu(x_k)p(y_k|x_k)}\right\}$$

MH filter makes the Markov chain reversible and hence  $\boldsymbol{\nu}$  is the stationary distribution.

## Joint distribution

$$\pi(x,y) \propto \exp\left(-f(x) - \frac{1}{2\eta} \|x - y\|^2\right)$$

Gibbs sampling:

- given  $x_k$ , sample  $y_k \sim \pi^{Y|X}(\cdot|x_k)$
- given  $y_k$ , sample  $x_{k+1} \sim \pi^{X|Y}(\cdot|y_{k+1})$

It is known from Gibbs sampling that  $(x_k, y_k)_{k\geq 1}$  form a reversible MC with stationary distribution  $\pi(x, y)$ , whose x-marginal is  $\nu(x) \propto \exp(-f(x))$ .

# **Proximal Frameworks**

# Optimization

## Algorithm Proximal Point Framework

1. 
$$y_k \leftarrow \underset{x}{\operatorname{argmin}} \frac{1}{2\eta} \|x - x_k\|^2 = x_k$$
  
2.  $x_{k+1} \leftarrow \underset{x}{\operatorname{argmin}} \left\{ f(x) + \frac{1}{2\eta} \|x - y_k\|^2 \right\}$ 

E.g., GD, SGD, AGD, Newton, Chambolle-Pock, ADMM, proximal bundle ...

## Sampling

Algorithm Alternating Sampling Framework (Shen, Tian and Lee 2021)

1. Sample 
$$y_k \sim \pi^{Y|X}(y \mid x_k) \propto \exp[-\frac{1}{2\eta} \|x_k - y\|^2]$$
  
2. Sample  $x_{k+1} \sim \pi^{X|Y}(x \mid y_k) \propto \exp[-f(x) - \frac{1}{2\eta} \|x - y_k\|^2]$ 

E.g., ULA, proximal Langevin algorithm, symmetric Langevin algorithm ...

(A1) f is semi-smooth, i.e., there exist  $\alpha \in [0,1]$  and  $L_{\alpha} > 0$ , s.t.

$$\|f'(u) - f'(v)\| \le L_{\alpha} \|u - v\|^{\alpha}, \quad \forall u, v \in \mathbb{R}^d$$

1)  $\alpha = 1$ , smooth, 2)  $\alpha = 0$ , nonsmooth, 3)  $0 < \alpha < 1$ , weakly smooth

(A2) f is composite, i.e., there exist  $\alpha_i \in [0,1]$  and  $L_{\alpha_i} > 0$ ,  $i = 1, \dots, n$ , s.t.

$$\|f'(u) - f'(v)\| \le \sum_{i=1}^n L_{\alpha_i} \|u - v\|^{\alpha_i}, \quad \forall u, v \in \mathbb{R}^d$$

 1 Regularized Cutting-Plane Method

2 Adaptive Proximal Bundle Method

Proximal Sampling Algorithm

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# Regularized Cutting-Plane Method

2 Adaptive Proximal Bundle Method

Proximal Sampling Algorithm

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# Regularized Cutting-plane Method

Proximal subproblem

$$f_y^{\eta}(x^*) = \min_{x \in \mathbb{R}^d} \left\{ f_y^{\eta}(x) = f(x) + \frac{1}{2\eta} \|x - y\|^2 \right\}$$

Algorithm Regularized Cutting-Plane Method (RCPM)

- 1. Let  $y \in \mathbb{R}^d$ ,  $\eta > 0$ , and  $\delta > 0$  be given, and set  $x_0 = \tilde{x}_0 = y$ , and j = 1.
- 2. Update  $f_j(x) = \max_{0 \le i \le j-1} \{ f(x_i) + \langle f'(x_i), x x_i \rangle \}.$
- 3. Compute

$$x_j = \operatorname*{argmin}_{x \in \mathbb{R}^d} \left\{ f_j^{\eta}(x) := f_j(x) + \frac{1}{2\eta} ||x - y||^2 \right\},$$

$$\tilde{x}_j = \operatorname{argmin}\left\{f_y^{\eta}(x) : x \in \{x_j, \tilde{x}_{j-1}\}\right\}.$$

4. If  $f_y^{\eta}(\tilde{x}_j) - f_j^{\eta}(x_j) \leq \delta$ , then stop and return  $J = j, x_J, \tilde{x}_J$ ; else, go to step 5.

5. Set  $j \leftarrow j + 1$  and go to step 2.

Recursively build up a cutting-plane model

$$f_j(x) = \max_{0 \le i \le j-1} \{ f(x_i) + \langle f'(x_i), x - x_i \rangle \}$$



# **Convergence** Analysis

Define  $\delta_j := f_y^\eta(\tilde{x}_j) - f_j^\eta(x_j)$ . Note that  $\delta_j \ge f_y^\eta(\tilde{x}_j) - f_j^\eta(x^*)$ .

Recall that we want to find  $\delta_J \leq \delta$ . If  $\delta_j > \delta$ , then  $(1 + \beta)\delta_j \leq \delta_{j-1}$  where

$$\beta = \frac{1}{2\eta} \left(\frac{\alpha+1}{L_{\alpha}}\right)^{\frac{2}{\alpha+1}} \delta^{\frac{1-\alpha}{\alpha+1}}$$

The complexity is  $\tilde{\mathcal{O}}(\beta^{-1}+1)$ 

## Theorem

If f is semi-smooth, RCPM takes  $\tilde{\mathcal{O}}\left(\eta L_{\alpha}^{\frac{2}{\alpha+1}}\left(\frac{1}{\delta}\right)^{\frac{1-\alpha}{\alpha+1}}+1\right)$  iterations to terminate. If f is composite, RCPM takes  $\tilde{\mathcal{O}}\left(\eta M+1\right)$  iterations to terminate, where

$$M = \sum_{i=1}^{n} \frac{L_{\alpha_i}^{\frac{1}{\alpha_i+1}}}{\left[(\alpha_i+1)\delta\right]^{\frac{1-\alpha_i}{\alpha_i+1}}}$$

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# Regularized Cutting-Plane Method

2 Adaptive Proximal Bundle Method

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Goal: 
$$\min_{x \in \mathbb{R}^d} f(x)$$
 where  $f$  is semi-smooth

proximal bundle method  $\approx$  proximal point framework + RCPM

Inner complexity is  $\tilde{\mathcal{O}}(\beta^{-1}+1)$ . In practice, it is desirable to have a relatively small number, say 10. Prescribe this number by choosing  $\beta_0 \in (0,1]$ ) and check

$$(1+\beta_0)\delta_j \le \delta_{j-1}.$$

If always true, we have complexity  $\tilde{\mathcal{O}}(\beta_0^{-1}+1)$ . Otherwise, reduce  $\eta$  in the next cycle. This is because  $(1+\beta)\delta_j \leq \delta_{j-1}$  where

$$\beta = \frac{1}{2\eta} \left(\frac{\alpha+1}{L_{\alpha}}\right)^{\frac{2}{\alpha+1}} \delta^{\frac{1-\alpha}{\alpha+1}}$$

This approach is adaptive and parameter-free.

# Adaptive Proximal Bundle Method

Inequality to check

$$(1+\beta_0)\delta_j \le \delta_{j-1}.$$
 (\*)

#### Algorithm Adaptive Proximal Bundle Method (APBM)

- 1. Let  $y_0 \in \mathbb{R}^d$ ,  $\eta_0 > 0$ ,  $\beta_0 \in (0,1]$ , and  $\varepsilon > 0$  be given, and set k = 1
- 2. Call RCPM with  $(y, \eta, \delta) = (y_{k-1}, \eta_{k-1}, \varepsilon/2)$  and output  $(y_k, \tilde{y}_k) = (x_J, \tilde{x}_J)$
- 3. In the execution of RCPM, if (\*) is always true, then set  $\eta_k = \eta_{k-1}$ ; otherwise, set  $\eta_k = \eta_{k-1}/2$
- 4. Set  $k \leftarrow k+1$  and go to step 2.

## Theorem

The complexity of APBM to find an  $\varepsilon$ -solution is  $\tilde{\mathcal{O}}$ 

$$\left(\frac{L_{\alpha}^{\frac{2}{\alpha+1}}\|y_0-x_*\|^2}{\varepsilon^{\frac{2}{\alpha+1}}}+1\right).$$

Regularized Cutting-Plane Method

2 Adaptive Proximal Bundle Method



# Sampling - Generation from Data

Sample from a probability distribution  $\nu \propto \exp(-f(x))$  where f has certain properties, such as convexity and smoothness



Extensively used in Bayesian inference and scientific computing



## Algorithm ASF

- 1. Sample  $y_k \sim \pi^{Y|X}(y \mid x_k) \propto \exp[-\frac{1}{2n} ||x_k y||^2]$
- 2. Sample  $x_{k+1} \sim \pi^{X|Y}(x \mid y_k) \propto \exp[-f(x) \frac{1}{2n} ||x y_k||^2]$

# Restricted Gaussian Oracle (RGO)

Given y, sample from

$$\pi^{X|Y}(\cdot|y) \propto \exp\left(-f(\cdot) - \frac{1}{2\eta} \|\cdot -y\|^2\right).$$

Without an implementable and provable RGO, ASF is only conceptual.

## Algorithm ASF

- 1. Sample  $y_k \sim \pi^{Y|X}(y \mid x_k) \propto \exp[-\frac{1}{2n} ||x_k y||^2]$
- 2. Sample  $x_{k+1} \sim \pi^{X|Y}(x \mid y_k) \propto \exp[-f(x) \frac{1}{2n} ||x y_k||^2]$

# Restricted Gaussian Oracle (RGO)

Given y, sample from

$$\pi^{X|Y}(\cdot|y) \propto \exp\left(-f(\cdot) - \frac{1}{2\eta} \|\cdot -y\|^2\right).$$

Without an implementable and provable RGO, ASF is only conceptual.

RGO: given y, sample from  $\exp(-f_y^{\eta}(x))$ 

## Algorithm RGO Rejection Sampling

- 1. Run RCPM to compute  $x_J$  and  $\tilde{x}_J$
- 2. Generate sample  $X \sim \exp(-h_1(x))$
- 3. Generate sample  $U \sim \mathcal{U}[0, 1]$

4. If

$$U \le \frac{\exp(-f_y^\eta(X))}{\exp(-h_1(X))},$$

then accept/return X; otherwise, reject X and go to step 2.

# **Rejection Sampling**

#### Define

$$h_1 := \frac{1}{2\eta} \| \cdot -x_J \|^2 + f_y^{\eta}(\tilde{x}_J) - \delta,$$
  
$$h_2 := \frac{1}{2\eta} \| \cdot -x^* \|^2 + \frac{L_\alpha}{\alpha + 1} \| \cdot -x^* \|^{\alpha + 1} + f_y^{\eta}(x^*).$$

We have  $h_1(x) \leq f_y^{\eta}(x) \leq h_2(x)$ .

The intuition is to build a proposal as a Gaussian close to  $\exp(-f_y^\eta(x))$ . Similar to the Laplace approximation of a density.

Known for RJ: X is an unbiased sample from  $\exp(-f_y^\eta(x))$  and the probability that X is accepted is

$$\mathbb{P}\left(U \leq \frac{\exp(-f_y^{\eta}(X))}{\exp(-h_1(X))}\right) = \frac{\int \exp(-f_y^{\eta}(x)) \mathrm{d}x}{\int \exp(-h_1(x)) \mathrm{d}x} \geq \frac{\int \exp(-h_2(x)) \mathrm{d}x}{\int \exp(-h_1(x)) \mathrm{d}x}$$

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# **Rejection Sampling Efficiency**

## Lemma

Let  $\alpha \in [0,1]$ ,  $\eta > 0$ ,  $a \ge 0$  and  $d \ge 1$ . If

$$2a(\eta d)^{(\alpha+1)/2} \le 1,$$

then

$$\int \exp\left(-\frac{1}{2\eta}\|x\|^2 - a\|x\|^{\alpha+1}\right) \mathrm{d}x \ge \frac{(2\pi\eta)^{d/2}}{2}.$$

# Proposition

Assume f is convex and  $L_{\alpha}$ -semi-smooth. If

$$\eta \le \frac{(\alpha+1)^{\frac{2}{\alpha+1}}}{(2L_{\alpha})^{\frac{2}{\alpha+1}}d},$$

then the expected number of iterations in the rejection sampling of RGO is at most  $2 \exp(\delta)$ .

# ASF Complexity

Another ingredient for total complexity: Convergence rate analysis of ASF

Theorem (Chen, Chewi, Salim and Wibisono 2022)

If  $\nu \propto \exp(-f)$  is log-concave, then  $x_k$  of ASF  $\sim 
ho_k$ , which satisfies

$$H_{\nu}(\rho_k) \le \frac{W_2^2(\rho_0, \nu)}{k\eta}.$$

If  $\nu \propto \exp(-f)$  satisfies log-Sobolev inequality with  $C_{\text{LSI}} > 0$ , then

$$H_{\nu}(\rho_k) \leq \frac{H_{\nu}(\rho_0)}{\left(1 + \frac{\eta}{C_{LSI}}\right)^{2k}}.$$

If  $\nu \propto \exp(-f)$  satisfies Poincaré inequality with  $C_{\rm PI} > 0$ , then

$$\chi_{\nu}^{2}(\rho_{k}) \leq \frac{\chi_{\nu}^{2}(\rho_{0})}{\left(1 + \frac{\eta}{C_{\mathrm{PI}}}\right)^{2k}}.$$

# Total Complexity

# Combining complexities of ASF, RGO, and RCPM

## Theorem

Assume f is convex and  $L_{\alpha}$ -semi-smooth, then ASF using the RGO implementation, initialized with  $\rho_0$  and stepsize  $\eta \asymp 1/(L_{\alpha}^{\frac{2}{\alpha+1}}d)$ , has the iteration-complexity bound

$$\mathcal{O}\left(\frac{L_{\alpha}^{\frac{2}{\alpha+1}}dW_{2}^{2}(\rho_{0},\nu)}{\varepsilon}\right) \tag{1}$$

to achieve  $\varepsilon$  error to the target  $\nu \propto \exp(-f)$  in terms of KL divergence. Each RGO requires  $\tilde{\mathcal{O}}\left(\frac{1}{d}\left(\frac{1}{\delta}\right)^{\frac{1-\alpha}{\alpha+1}}+1\right)$  subgradient evaluations of f and  $2\exp(\delta)$  rejection steps in expectation.

Generalize to LSI, PI, composite.

## Algorithm ASF

- 1. Sample  $y_k \sim \pi^{Y|X}(y \mid x_k) \propto \exp[-\frac{1}{2\eta} \|x_k y\|^2]$
- 2. Sample  $x_{k+1} \sim \pi^{X|Y}(x \mid y_k) \propto \exp[-f(x) \frac{1}{2\eta} ||x y_k||^2]$

## Algorithm ULA

1. Sample 
$$y_k \sim \pi^{Y|X}(y \mid x_k) \propto \exp[-\frac{1}{2\eta} \|x_k - y\|^2]$$
  
2. Sample  $x_{k+1} \sim e^{-\langle \nabla f(y_k), x - y_k \rangle - \frac{1}{2\eta} \|x - y_k\|^2} \propto e^{-\frac{1}{2\eta} \|x - (y_k - \eta \nabla f(y_k))\|^2}$ 

$$x_{k+1} = y_k - \eta \nabla f(y_k) + \sqrt{\eta} z_k, \quad z_k \sim N(0, I),$$
  
$$y_{k+1} = x_{k+1} + \sqrt{\eta} z'_k, \quad z'_k \sim N(0, I).$$

 $\implies y_{k+1} = y_k - \eta \nabla f(y_k) + \sqrt{\eta} (z_k + z'_k) = y_k - \eta \nabla f(y_k) + \sqrt{2\eta} z, \quad z \sim N(0, I)$ 

ULA can be viewed as ASF with RGO implemented without rejection

$$h_1(x) = f(y_k) + \langle f'(y_k), x - y_k \rangle + \frac{1}{2\eta} \|x - y_k\|^2 \le f(x) + \frac{1}{2\eta} \|x - y_k\|^2 = f_{y_k}^{\eta}(x)$$

# Conclusion

## Interplay between optimization and sampling

- Proximal frameworks
  - Proximal point framework
  - Alternating sampling framework
- Proximal oracles
  - Proximal map
  - Restricted Gaussian oracle
- Applications
  - Adaptive proximal bundle method
  - Proximal sampling algorithm
- Simplifications
  - Subgradient method
  - Unadjusted Langevin algorithm

Future directions: Parameter-free sampling? Acceleration in sampling?

- Chen, Chewi, Salim, and Wibisono. Improved Analysis for a Proximal Algorithm for Sampling. Conference on Learning Theory 2022
- Jordan, Kinderlehrer, and Otto. The variational formulation of the Fokker–Planck equation. SIAM Journal on Mathematical Analysis 1998
- Lee, Shen, and Tian. Structured Logconcave Sampling with a Restricted Gaussian Oracle. Conference on Learning Theory 2021

# Thank you!